

## FD422S Series Servo Driver

### FEATURES

- **Input Voltage Range From 176-253VAC**
- **Rated Current is (RMS) 4A**
- **200-750 Watt Power Range**
- **Position, Speed, and Torque Control**
- **RS232 & RS485 (LA) or RS232 & CAN BUS (AA/CA)**
- **Communication Protocol: MODBUS**
- **Requires 2500PPR Encoder Input**
- **Communication Software**
  - **Configure Parameters**
  - **I/O Signal Monitoring**
  - **Speed and Position Curves**
  - **Gain Adjustments**
- **Programmable Inputs and Outputs**
  - **7 Inputs / 4 Outputs**
- **2 Analog Inputs**
- **CAN BUS Port and CANopen Optional**
- **CE Certified**



### DESCRIPTION

The FD422S Series Servo Drives are a great fit for applications requiring position, speed and/or torque control methods. The 2S version Servo Driver supports motors with higher resolution encoders: 16-bit multi turn encoder, 17-bit single turn encoder, 20-bit single turn encoder, and 17-bit mechanical encoder. The uniqueness of this Servo Drive is the flexibility of using a single Servo Drive that can accommodate motors with power ratings ranging from 200-750W. Also, it is designed to switch dynamically among different control methods for more flexible operation. The FD422S Series Servo Drive operates with 176-253VAC input. The FD422S-LA-000 Servo Drive comes standard with RS232 and RS485 communication ports. A CAN BUS is an optional port that is available upon request. The FD422S-AA-000 and FD422S-CA-000 Servo Drives come standard with RS232 and CAN BUS communication ports. These drives can be operated using MODBUS Protocol or the free, Easy-to-Use Software.

### SPECIFICATIONS

Servo Driver	Servo Motor	Description	Power/Brake Cable	Encoder Cable	Rated Speed/ Rated Torque/ Rated Current
FD422S-LA-000 FD422S-CA-000 FD422S-AA-000	SMH60S-0020-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCA-05-KH	3000rpm/  0.64Nm/  1.6A
	SMH60S-0020-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/BRA-05-KL		
	SMH60S-0020-30AAK-3LKN	HFO Standard Connector	MOT-005-05-KC0	ENCCA-05-KC0	
	SMH60S-0020-30AAK-3LKM	Intercontec Connector	MOT-005-05-KM1	ENCCA-05-KM1	
	SMH60S-0020-30ABK-3LKM	Intercontec Connector w/Brake	MOT-005-05-KM1-B		
	SMH60S-0040-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCA-05-KH	3000rpm/  1.27Nm/  3.1A
	SMH60S-0040-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/BRA-05-KL		
	SMH60S-0040-30AAK-3LKN	HFO Standard Connector	MOT-005-05-KC0	ENCCA-05-KC0	
	SMH60S-0040-30AAK-3LKM	Intercontec Connector	MOT-005-05-KM1	ENCCA-05-KM1	
	SMH60S-0040-30ABK-3LKM	Intercontec Connector w/Brake	MOT-005-05-KM1-B		

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Servo Driver	Servo Motor	Description	Power/Brake Cable	Encoder Cable	Rated Speed/ Rated Torque/ Rated Current
<b>FD422S-LA-000</b> <b>FD422S-CA-000</b> <b>FD422S-AA-000</b>	SMH80S-0075-30AAK-3LKH	Cable Connector	MOT-005-05-KL	ENCCA-05-KH	3000rpm/ 2.39Nm/ 3.9A
	SMH80S-0075-30ABK-3LKH	Cable Connector and Brake	MOT-005-05-KL/ BRA-05-KL		
	SMH80S-0075-30AAK-3LKN	HFO Standard Connector	MOT-005-05-KC0	ENCCA-05-KC0	
	SMH80S-0075-30AAK-3LKM	Intercontec Connector	MOT-005-05-KM1	ENCCA-05-KM1	
	SMH80S-0075-30ABK-3LKM	Intercontec Connector w/Brake	MOT-005-05-KM1-B		

Model Parameter		KNC-SRV-FD422S Series
Operation Environment	Operating Temperature	0°C ~ 40°C (ice free)
	Storage Temperature	-10°C ~ 70°C (ice free)
	Humidity (Non-Condensing)	5 ~ 90% RH
	Protection Class	IP20
	Installation Environment	Installed in a Dust-Free, Dry and Lockable Environment (Such as in a Electrical Cabinet)
	Installation Mode	Vertical Installation
	Altitude	No Power Limitation Below 1000m
	Atmospheric Pressure	86kpa-106kpa

Model Parameter		FD422-■A-000 Series
Power	Main Supply Voltage	Single-Phase AC 220V -20/+15% 47~63Hz
	Control Circuit Voltage	18VDC~30VDC 1A
Current	Rated Current (RMS)	4A
	Peak Current (PEAK)	15A
Feedback Signal		2500PPR (Incremental Encoder with 5V Supply)
Brake Chopper		Use an External Braking Resistor According to Application, Mainly in Occasion of Quick Stop.
Brake Chopper Threshold		DC380V ± 5V
Over-Voltage Alarming Threshold		DC400V ± 5V
Under-Voltage Alarming Threshold		DC200V ± 5V
Cooling Method		Natural Air Cooling
Weight		1.2 Kg
Digital Input	Input Specification	7 Digital Inputs, with COM1 Terminal for PNP (High Level Valid 12.5-30V) or NPN (Low Level Valid) connection.
	Input Function	Define Freely According to Requirement, Supporting Following Functions: Driver Enable, Driver Fault Reset, Driver Mode Control, Proportional Control, Positive Limit, Negative Limit, Homing Signal, Reverse Command, Internal Speed Section Control, Internal Positive Section Control, Quick Stop, Start Homing, Active Command, Switch Electronic Gear Ratio, Switch Gain.
Digital Output	Output Specification	5 Digital outputs, OUT1~OUT4 Current is 100mA, BR+/BR- (Brake Control Output) Current is 500mA, Can Drive Brake Device Directly.
	Output Function	Define Freely According to Requirement, Supporting Following Functions: Driver Ready, Driver Fault, Positon Reached, Motor at Zero Speed, Motor Brake, Motor Speed Reached, Z Signal, Maximum Speed Obtained in Torque Mode, Motor Brake, Position Limiting, Reference Found, Multi-Position Reached
	Analog Input	2 Analog input, can be used to control speed and Torque, the input range is -10V~10V
	Encoder Signal Output	Output the Encoder Signal of Motor, Used in Multiple Axis Synchronous Control, Supports 2MHz at Most
	RS232	The Max. Baudrate os 115.2KHz, Use JD-PC Software to communicate with PC, or Via Free Protocol to communicate with Controller.
	Protection Functions	Over-Voltage Protection, Under-Voltage Protection, Motor Over-Heat Protection (I <sup>2</sup> T), Short-Circuit Protection, Drive Over-Heat Protection, Etc.
RS485		The max. baudrate is 115.2 KHz, use Modbus RTU protocol to communicate with controller.
CAN BUS		The max baudrate is 1 MHz, Communicates with Controller via CANopen Protocol

**Note:** □=L: Communication Port RS232, RS485  
 □=A/C: Communication Port RS232, CANopen

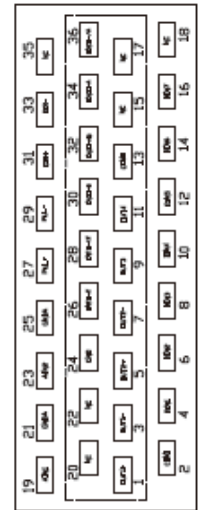
# FD422S Series Servo Driver



## Digital Input/Output Interface

PIN No.	Signal	PIN No.	Signal	PIN No.	Signal	PIN No.	Signal
2	COM1	1	OUT1+	20	NC	19	AIN1
4	DIN1	3	OUT1-	22	NC	21	GNDA
6	DIN2	5	OUT2+	24	GND	23	AIN2
8	DIN3	7	OUT2-	26	ENCO-Z	25	GNDA
10	DIN4	9	OUT3	28	ENCO-Z	27	PUL+
12	DIN5	11	OUT4	30	ENCO-B	29	PUL-
14	DIN6	13	COM0	32	ENCO-B	31	DIR+
16	DIN7	15	NC	34	ENCO-A	33	DIR-
18	NC	17	NC	36	ENCO-A	35	NC

X1



## RS485

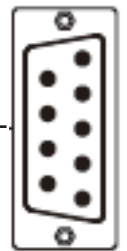
PIN Number	Signal
1	NC
2	RX+
3	TX+
4	NC
5	GND
6	+5V
7	RX-
8	TX-
9	NC

## CAN

PIN Number	Signal
1	NC
2	CAN_L
3	GND
4	NC
5	NC
6	NC
7	CAN_H
8	NC
9	NC

Male: CANbus  
Communication Port  
Female:RS485  
Communication Port

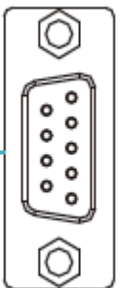
X4



## RS232

PIN Number	Signal
1	NC
2	TX
3	RX
4	NC
5	GND
6	NC
7	NC
8	NC
9	NC

X5

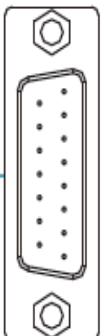


## ENCODER IN

PIN No.	Incremental Encoder Signal	PIN No.	Incremental Encoder Signal	PIN No.	Communication Encoder Signal	PIN No.	Communication Encoder Signal
1	+5V	9	GND	1	+5V	9	GND
2	A	10	/A	2	NC	10	NC
3	B	11	/B	3	NC	11	NC
4	Z	12	/Z	4	NC	12	NC
5	U	13	/U	5	NC	13	NC
6	V	14	/V	6	NC	14	NC
7	W	15	/W	7	SD	15	/SD
8	PTC_IN			8	NC		

X6

Motor Encoder  
Input Port



INTERFACE DESCRIPTION